Turtle Field Quick Reference

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Turtle Graphics

	Java methods in Turtle class	
connect to server	Turtle.new(String hostname)	use TCP port 2222
clear screen	void clr(void)	
home position	void home(void)	origin is the center of square
pen up	void pu(void)	
pen down	void pd(void)	
step forward	void fd(float step)	unit of length: pixel
step back	void bk(float step)	
jump	void jump(double x, double y)	
relative jump	void rjump(double dx, double dy)	
turn left	void lt(double angle)	unit of angle: degree
turn right	void rt(double angle)	
print string	void say(String string)	
line mode	void line(void)	
brush mode	void brush(void)	
filling mode	void fill(void)	max # of vertices in filling mode: 6
display card	void card(int type, double x, double y)	type: 1..53
clear card	void clrcard(void)	
query curr. position	double[ ] q_pos(void)	
query heading direction	double q_dir(void)	0.0 < r, g, b < 1.0
pen color	void col(double r, double g, double b)	
background color	void bgc(double r, double g, double b)	

Methods to be called on events

- void hit_by_bullet(int time)
- void run_into_turtle(int time)
- void run_into_donut(int time)
- void run_into_stone(int time)
- void run_into_wall(int time)
- void found_coin(int time)
- void detected_by_finder(int time)
- void detected_by_radar(int time)
- void got_message(int time)

time code is passed

Scoring

initial score of each: 100
point to loose for each shoot: -1
hitting other turtle: +10
hit by bullet:-30
hitting donut within short distance: +10
when score < 0, disconnected

Regulations/limitations in battle (robot) mode

step size of FD & BK: up to 2 pixels
turning angle: up to 3 degrees
field is surrounded by rigid walls

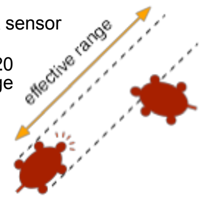
only single bullet can exist at a moment in the field for each turtle

Battles & robot simulations

	methods	
switch to battle mode	void bmode(void)	
switch to graphics mode	void gmode(void)	
shoot a bullet	void fire(void)	
set nickname	void nm(String name)	
set my team number	void tm(int team_id)	0<=team_id<=4
query number of objects	int q_nt(void)	returns # of turtles and donuts
query to finder	int q_finder(void)	returns code →
set range of finder	void rf(double range)	
query to angular radar	double q_radar(void)	returns angle →
query to sonar	boolean[ ] q_sonar(void)	returns [left, front, right]
query my current score	int q_score(void)	
query team id of turtle met just before	int q_tm(void)	use this call after Q_FINDER or Q_RADAR
put a robot turtle in the field	void robot(void)	
scatter a donut in the field	void donut(void)	max 10 donuts for each
scatter a coin in the field	void coin(void)	
borrow 10 coins from the TF owner	void borrowcoin(void)	max 300 coins in the field
drop a coin at current position	void dropcoin(void)	
pick one coin near current position	void pickcoin(void)	
check number of coin at near distance	int q_coin(void)	
broadcast message to team members	void bcas(String msg)	
query team message	TeamMessage q_bcas()	

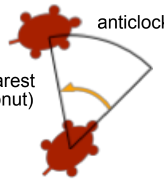
FINDER front sensor

default: 20
use rf() to change



result code = 0: no objects within effective range
1: turtle 2: donut 3: stone 4: wall found

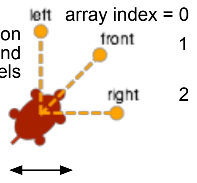
RADAR angular sensor



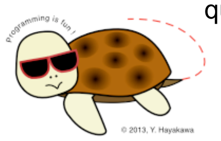
measurement error: ±20 deg

SONAR obstacle detector

for each direction
false: no obstacle, true: obstacle found
within 20 pixels



size of turtle: 20 pixels in diameter



C, Ruby, and Python APIs are available at TurtleField web site:
http://seaotter.cite.tohoku.ac.jp/coda/tfield/index.html

Usage of Turtle Field server

right click on screen to pop up menu

clear field	clear drawing
erase zombie	erase turtles that lost TCP connections
toggle graphics/battle mode	in battle mode, background texture changes
toggle private/public mode	in public mode connections from any addr. are accepted. window title bar changes
capture screen	save screen shot in home (UNIX) or desktop (Windows)
kill all turtles	
exit	

press capital M: enter maze mode
3: toggle b/w 2D and 3D modes
http port for Turtle Field Live: 2280